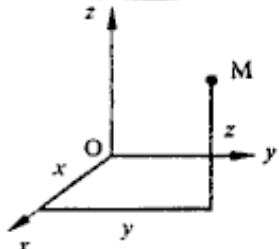
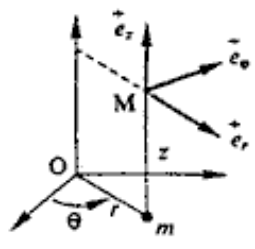
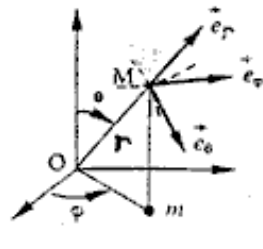


Opérateurs vectoriels

I) Les différents opérateurs

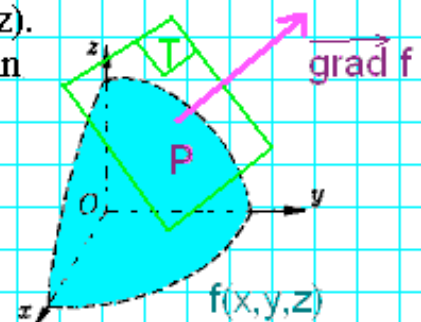
	CARTÉSIENNES	CYLINDRIQUES	SPHÉRIQUES
DÉFINITION	 <p>$V = V(x, y, z)$</p> $\vec{a} \begin{cases} a_x \\ a_y \\ a_z \end{cases}$	 <p>$V = V(r, \theta, z)$</p> $\vec{a} \begin{cases} a_r \\ a_\theta \\ a_z \end{cases}$	 <p>$V = V(r, \theta, \varphi)$</p> $\vec{a} \begin{cases} a_r \\ a_\theta \\ a_\varphi \end{cases}$
GRADIENT	$\vec{\nabla} V \begin{cases} \frac{\partial V}{\partial x} \\ \frac{\partial V}{\partial y} \\ \frac{\partial V}{\partial z} \end{cases}$	$\vec{\nabla} V \begin{cases} \frac{\partial V}{\partial r} \\ \frac{1}{r} \frac{\partial V}{\partial \theta} \\ \frac{\partial V}{\partial z} \end{cases}$	$\vec{\nabla} V \begin{cases} \frac{\partial V}{\partial r} \\ \frac{1}{r} \frac{\partial V}{\partial \theta} \\ \frac{1}{r \sin \theta} \frac{\partial V}{\partial \varphi} \end{cases}$
DIVERGENCE	$\operatorname{div} \vec{a} = \frac{\partial a_x}{\partial x} + \frac{\partial a_y}{\partial y} + \frac{\partial a_z}{\partial z}$	$\operatorname{div} \vec{a} = \frac{1}{r} \frac{\partial}{\partial r} (ra_r) + \frac{1}{r} \frac{\partial a_\theta}{\partial \theta} + \frac{\partial a_z}{\partial z}$	$\operatorname{div} \vec{a} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 a_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (a_\theta \sin \theta) + \frac{1}{r \sin \theta} \frac{\partial a_\varphi}{\partial \varphi}$
ROTATIONNEL	$\operatorname{rot} \vec{a} \begin{cases} \frac{\partial a_z}{\partial y} - \frac{\partial a_y}{\partial z} \\ \frac{\partial a_x}{\partial z} - \frac{\partial a_z}{\partial x} \\ \frac{\partial a_y}{\partial x} - \frac{\partial a_x}{\partial y} \end{cases}$	$\operatorname{rot} \vec{a} \begin{cases} \frac{1}{r} \frac{\partial a_z}{\partial \theta} - \frac{\partial a_\theta}{\partial z} \\ \frac{\partial a_r}{\partial z} - \frac{\partial a_z}{\partial r} \\ \frac{1}{r} \left[\frac{\partial (ra_\theta)}{\partial r} - \frac{\partial a_r}{\partial \theta} \right] \end{cases}$	$\operatorname{rot} \vec{a} \begin{cases} \frac{1}{r \sin \theta} \left(\frac{\partial}{\partial \theta} (a_\varphi \sin \theta) - \frac{\partial a_\varphi}{\partial \varphi} \right) \\ \frac{1}{r \sin \theta} \frac{\partial a_r}{\partial \varphi} - \frac{1}{r} \frac{\partial}{\partial r} (ra_\varphi) \\ \frac{1}{r} \left[\frac{\partial}{\partial r} (ra_\theta) - \frac{\partial a_r}{\partial \theta} \right] \end{cases}$
LAPLACIEN	$\Delta V = \frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial y^2} + \frac{\partial^2 V}{\partial z^2}$	$\Delta V = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial V}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2 V}{\partial \theta^2} + \frac{\partial^2 V}{\partial z^2}$	$\Delta V = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial V}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial V}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 V}{\partial \varphi^2}$

coordonnées	cartésiennes	cylindriques	sphériques
$d\vec{l}$	$dx \vec{u}_x + dy \vec{u}_y + dz \vec{u}_z$	$d\rho \vec{u}_\rho + \rho d\theta \vec{u}_\theta + dz \vec{u}_z$	$dr \vec{u}_r + r d\theta \vec{u}_\theta + r \sin \theta d\varphi \vec{u}_\varphi$
$\vec{\text{grad}} f(M)$	$\frac{\partial f}{\partial x} \vec{u}_x + \frac{\partial f}{\partial y} \vec{u}_y + \frac{\partial f}{\partial z} \vec{u}_z$	$\frac{\partial f}{\partial \rho} \vec{u}_\rho + \frac{1}{\rho} \frac{\partial f}{\partial \theta} \vec{u}_\theta + \frac{\partial f}{\partial z} \vec{u}_z$	$\frac{\partial f}{\partial r} \vec{u}_r + \frac{1}{r} \frac{\partial f}{\partial \theta} \vec{u}_\theta + \frac{1}{r \sin \theta} \frac{\partial f}{\partial \varphi} \vec{u}_\varphi$
$\text{div } \vec{U}(M)$	$\frac{\partial U_x}{\partial x} + \frac{\partial U_y}{\partial y} + \frac{\partial U_z}{\partial z}$	$\frac{1}{\rho} \left(\frac{\partial(\rho U_\rho)}{\partial \rho} + \frac{\partial U_\theta}{\partial \theta} \right) + \frac{\partial U_z}{\partial z}$	$\frac{1}{r^2} \frac{\partial(r^2 U_r)}{\partial r} + \frac{1}{r \sin \theta} \frac{\partial(U_\theta \sin \theta)}{\partial \theta} + \frac{1}{r \sin \theta} \frac{\partial U_\varphi}{\partial \varphi}$
$\vec{\text{rot}} U(M)$	$\left[\frac{\partial U_z}{\partial y} - \frac{\partial U_y}{\partial z} \right] \vec{u}_x +$ $\left[\frac{\partial U_x}{\partial z} - \frac{\partial U_z}{\partial x} \right] \vec{u}_y +$ $\left[\frac{\partial U_y}{\partial x} - \frac{\partial U_x}{\partial y} \right] \vec{u}_z +$	$\left[\frac{1}{\rho} \frac{\partial U_z}{\partial \theta} - \frac{\partial U_\theta}{\partial z} \right] \vec{u}_\rho +$ $\left[\frac{\partial U_\rho}{\partial z} - \frac{\partial U_z}{\partial \rho} \right] \vec{u}_\theta +$ $\left[\frac{1}{\rho} \frac{\partial(\rho U_\theta)}{\partial \rho} - \frac{1}{\rho} \frac{\partial U_\rho}{\partial \theta} \right] \vec{u}_z$	$\frac{1}{r \sin \theta} \left[\frac{\partial(\sin \theta U_\varphi)}{\partial \theta} - \frac{\partial U_\theta}{\partial \varphi} \right] \vec{u}_r +$ $\left[\frac{1}{r \sin \theta} \frac{\partial U_r}{\partial \varphi} - \frac{1}{r} \frac{\partial(r U_\varphi)}{\partial r} \right] \vec{u}_\theta +$ $\frac{1}{r} \left[\frac{\partial(r U_\theta)}{\partial r} - \frac{\partial U_r}{\partial \theta} \right] \vec{u}_\varphi$
$\Delta f(M)$	$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2}$	$\frac{1}{\rho} \frac{\partial}{\partial \rho} \left(\rho \frac{\partial f}{\partial \rho} \right) + \frac{1}{\rho^2} \frac{\partial^2 f}{\partial \theta^2} + \frac{\partial^2 f}{\partial z^2}$	$\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial f}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \varphi^2}$

II) Interprétation géométrique des opérateurs vectoriels

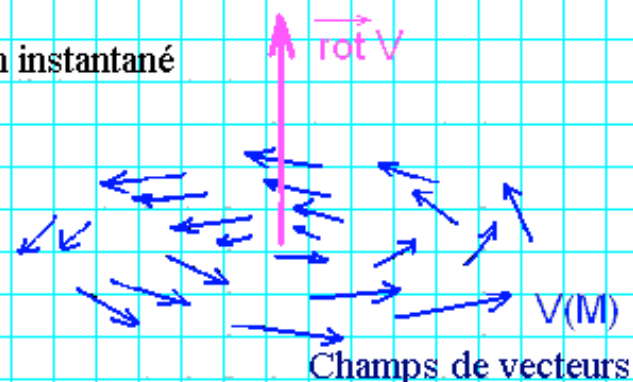
1) Le gradient

Soit une surface définie par une fonction $f(x,y,z)$.
Le gradient de f définit le vecteur normal au plan tangent en tout point de cette surface.



2) Le rotationnel

Le rotationnel "définit" le centre de rotation instantané d'un champs de vecteurs.



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III) Relations entre opérateurs vectoriels

$$\operatorname{div} \vec{V} = \vec{\nabla} \cdot \vec{V}$$

$$\operatorname{rot} \vec{V} = \vec{\nabla} \wedge \vec{V}$$

IV) Intervention des opérateurs vectoriels dans les intégrales

$$\iint \vec{E} \cdot \vec{n} \, dS = \iiint \operatorname{div} \vec{E} \, dv$$

Théorème de Gauss

$$\int \vec{A} \cdot d\vec{l} = \iint \operatorname{rot} \vec{A} \cdot \vec{n} \, dS$$

Théorème de Stokes

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